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Modeling and Optimization of Parallel and Distributed Embedded Systems - Ebook written by Arslan Munir, Ann Gordon-Ross, Sanjay Ranka. Read this book using Google Play Books app on your PC, android, iOS devices. Download for offline reading, highlight, bookmark or take notes while you read Modeling and Optimization of Parallel and Distributed Embedded Systems.

Modeling and Optimization of Parallel and Distributed ...

This paper describes the development and performance optimization of a parallel computing infrastructure for an unstructured-mesh global model (GRIST; Global-to-Regional Integrated forecast SysTem). The focus is on three major aspects that facilitate rapid iterative development, including parallel computing, index optimization and an efficient group I/O strategy.

Development and performance optimization of a parallel ...

Parallel flow condenser (PFC), which is widely used in automobile air conditioning (AAC) industries, was modeled and optimized in this paper. A sample of designed and manufactured condenser of this type was modeled and tested. In the proposed physical model the condenser is divided into three regions of superheat, saturated (two-phase) and subcooled.

Modeling and multi-objective optimization of parallel flow ...

An integrated model and simulation of the parallel hydraulic hybrid bus is built based on AMESim, which is used to model the hydraulic powertrain and conventional bus driveline, and interlinked with a Matlab/Simulink/Stateflow model of the control unit. ... Integrated modeling and optimization of a parallel hydraulic hybrid bus. Y. Yan 1, G ...

Integrated modeling and optimization of a parallel ...

Abstract. As a typical Gauss-Seidel method, the inherent strong data dependency of lower-upper symmetric Gauss-Seidel (LU-SGS) poses tough challenges for shared-memory parallelization. On early multi-core processors, the pipelined parallel LU-SGS approach achieves promising scalability. However, on emerging many-core processors such as Xeon Phi, experience from our in-

house high-order CFD program show that the parallel efficiency drops dramatically to less than 25%.

Performance modeling and optimization of parallel LU-SGS ...

The main disadvantage of parallel robots is their small workspace in comparison to serial arms of similar size. Furthermore, the manipulability of parallel robots is often poor in some regions of the (already small) workspace. Another problematic issue is effective modeling of parallel robot dynamics, often needed for control algorithms.

Optimal Design and Modeling of Spatial Parallel ...

A screw theory based method that is efficient in modeling full Jacobian matrix for parallel mechanisms is used here. Express the angular velocity of the moving platform with respect to the global coordinate system using a vector w , and the linear velocity of a point in the moving platform that is instantaneously coincident with the origin of the reference coordinate system using a vector v_p .

Kinematic modeling and optimization of a new ...

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Modeling and Optimization of Parallel and Distributed ...

The Parallel Computing Systems (PCS) theme performs research on the design, programming and run-time management of multi-core and multi-processor computer systems. The modeling, analysis and optimization of the extra-functional aspects of these systems, such as performance, power/energy consumption but also the degree of productivity to design and program these systems, play a pivotal role in...

Parallel Computing Systems (PCS) - UvA

This concern has directly impacted the development of the novel theoretical research areas and products. This new book provides information about fundamental topics of serial and parallel manipulators such as kinematics & dynamics modeling, optimization, control algorithms and design strategies.

Serial and Parallel Robot Manipulators - Kinematics ...

The input information is introduced as the inhibition times of individual oscillators, and the output information is coded in the number of activator maxima observed on a selected oscillator. We have used the Oregonator model to simulate the network time evolution and the evolutionary optimization to find the best network for the considered task.