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 IEEE Trans Neural Syst Rehabil Eng. 2007 Sep;15 (3):387-400. A robot and control algorithm that can synchronously assist in naturalistic motion during body-weight-supported gait training following neurologic injury. Aoyagi D (1), Ichinose WE, Harkema SJ, Reinkensmeyer DJ, Bobrow JE.

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In Visser, Ribeiro, Ohashi, and Dellaert, editors, RoboCup-2007, Springer Verlag, 2008. A Neural Network-Based Approach to Robot Motion Control Uli Grasemann, Daniel Stronger, and Peter Stone Department of Computer Sciences University of Texas at Austin Austin, TX 78712, USA {uli,stronger,pstone}@cs.utexas.edu Abstract.

A Neural Network-Based Approach to Robot Motion Control

Abstract: Robot navigation in the presence of humans raises new issues for motion planning and control when the humans must be

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Dynamic window based approach to mobile robot motion

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Industrial robot motion control with real-time Java and EtherCAT Robertz, Sven LU ; Nilsson, Klas LU ; Henriksson, Roger LU and Blomdell, Anders LU (2007) 12th IEEE Conference on Emerging Technologies and Factory Automation p.1453-1456

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Robotic control is the system that contributes to the movement of robots. This involves the mechanical aspects and program systems that makes possible to control robots. Robotics could be controlled in various ways, which includes using manual control, wireless control, semi-autonomous (which is a mix of fully automatic and wireless control), and fully autonomous (which is when it uses AI to ...

Robot control - Wikipedia

Ahmed R.M., Ananiev A.V., Kalaykov I.G. (2009) Compliant Motion Control for Safe Human Robot Interaction. In: Kozłowski K.R. (eds) Robot Motion and Control 2009. Lecture Notes in Control and Information Sciences, vol 396.